



PAPER DIGEST

CERTIFICATE OF RECOGNITION

MOST INFLUENTIAL ICML 2019 PAPER

This is to certify that the paper

Learning Latent Dynamics for Planning from Pixels

Danijar Hafner, Timothy Lillicrap, Ian Fischer, Ruben Villegas, David Ha, Honglak Lee, and James Davidson

presented at the International Conference on Machine Learning (ICML), 2019

is recognized among the Most Influential ICML 2019 Papers



Paper Digest
New York, New York



Edition 2026-03
Issued 2026-03 - Impact Factor 8

[Verify this certificate at paperdigest.org](https://paperdigest.org)

Certificate ID 47e06d91b84212d2 - Ranking constructed from citations in research papers and granted patents.

Scan to verify

